

Exam 2013

Answers

Mathematics for Multimedia Applications
Medialogy

11. June 2013

Formalities

This exam set consists of 6 pages, in which there are 10 problems. You are allowed to use books, notes etc. You are *not* allowed to use electronic devices such as calculators, computers or cell phones.

A number of points is indicated for every sub-problem. The sum of these points equals 100.

Date and time for the exam: 11. June, 9:00 - 13:00.

You must indicate the following on each page:

- Full name
- Study number
- Page number

On the first page, you must indicate

- The total number of pages.

Good luck!

Problems

Problem 1.

1.a. (3 points) Differentiate the function $f(x) = \sin(5x) + 3 \cos(x)$.

$$f'(x) = 5 \cos(5x) - 3 \sin(x)$$

1.b. (3 points) Differentiate the function $g(x) = \ln(e^x + 2)$.

$$g'(x) = \frac{e^x}{e^x + 2}$$

Problem 2. The position function of a particle moving along a horizontal straight line is given by

$$x(t) = 3t^2 - 12t + 7$$

$$v(t) = 6t - 12$$

$$a(t) = 6$$

2.a. (3 points) Find the velocity $v(t)$ and the acceleration $a(t)$ of the particle.

2.b. (3 points) Find the position of the particle when its velocity is zero.

$$x(2) = \underline{\underline{-5}}$$

Problem 3.

3.a. (2 points) Find a solution of the equation $\sin^2(x) = 0$.

$$x = 0$$

3.b. (3 points) Describe all solutions of the equation $\sin^2(x) = 0$.

$$x = \pi p, \quad p \in \mathbb{Z}$$

3.c. (3 points) Prove that the following trigonometric identity holds:

$$(1 + \cos(\theta))(1 - \cos(\theta)) = \sin^2(\theta)$$

$$(1 + \cos(\theta)) \cdot (1 - \cos(\theta)) = 1 + \cos(\theta) - \cos(\theta) - \cos^2(\theta) = 1 - \cos^2(\theta) = \sin^2(\theta)$$

↑
since $\cos^2(\theta) + \sin^2(\theta) = 1$

Problem 4.

4.a. (3 points) Calculate the sum

$$\sum_{i=1}^4 (i^2 - 1)$$

$$26$$

4.b. (4 points) Calculate the sum

$$\sum_{i=1}^{100} (3i^2 - i)$$

$$1010000$$

$$F(x) = x^2 - \frac{1}{3}x^4$$

$$G(x) = -\frac{1}{2}\cos(2x)$$

Problem 5. Consider the two functions $f(x) = 2x - \frac{4}{3}x^3$ and $g(x) = \sin(2x)$.

5.a. (4 points) Find antiderivatives $F(x)$ and $G(x)$ of the functions $f(x)$ and $g(x)$.

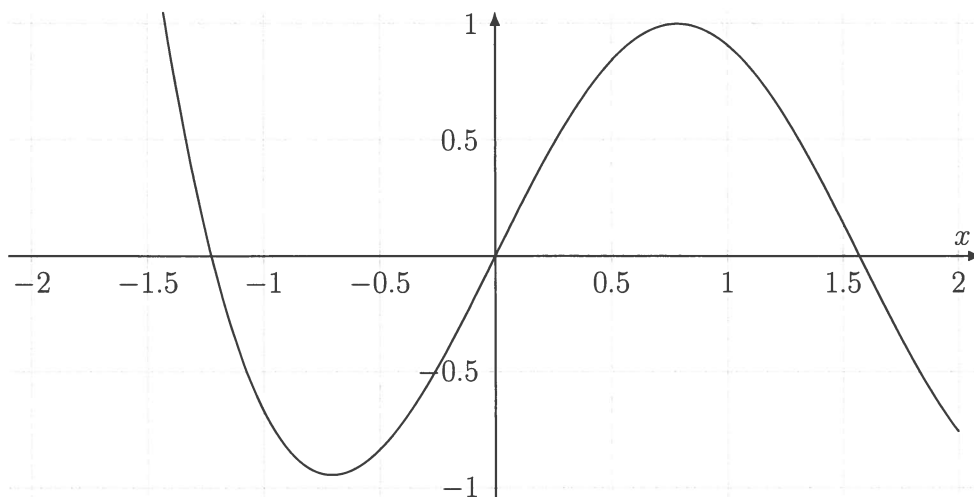
5.b. (3 points) Evaluate the integrals $\int_{-1}^0 f(x)dx$ and $\int_0^{\pi/2} g(x)dx$.

$$-\frac{2}{3} \text{ and } 1$$

Define the function $h(x)$ by

$$h(x) = \begin{cases} f(x) & \text{if } x < 0, \\ g(x) & \text{if } x \geq 0, \end{cases}$$

where $f(x)$ and $g(x)$ are the functions above. The graph of $h(x)$ looks as follows:



5.c. (3 points) Find $\int_{-1}^{\pi/2} h(x)dx$.

$$\frac{1}{3}$$

Problem 6. Let P, Q, R and S be points in 3D-space with coordinates $(1, 3, -1), (2, 3, 0), (4, 3, 2)$ and $(6, 5, 3)$ respectively.

$$\vec{PQ} = (1, 0, 1)$$

$$\vec{RS} = (2, 2, 1)$$

6.a. (2 points) Find \vec{PQ} and \vec{RS} .

6.b. (3 points) Find parametric equations for the line ℓ_1 that passes through P and Q and the line ℓ_2 that passes through R and S .

$$(x, y, z) = (1, 3, -1) + t(1, 0, 1)$$

$$(x, y, z) = (4, 3, 2) + s(2, 2, 1)$$

6.c. (3 points) Show that the two lines ℓ_1 and ℓ_2 intersect at the point R .

$$\text{Put } s=0, t=3.$$

6.d. (2 points) Compute the dot product $\vec{PQ} \cdot \vec{RS}$.

$$3$$

6.e. (3 points) Compute the angle between the lines ℓ_1 and ℓ_2 .

$$\frac{\pi}{4}$$

Problem 7. Let O , P and Q be the points in 3D-space with coordinates $(0, 0, 0)$, $(1, 0, 1)$ and $(3, 1, -1)$ respectively.

- 7.a. (3 points) Compute the cross product $\vec{OP} \times \vec{OQ}$. $(-1, 4, 1)$
 7.b. (3 points) Find the area of the triangle with vertices O , P and Q . $\frac{\sqrt{18}}{2}$
 7.c. (3 points) Find an equation for the plane through O , P and Q . $-x + 4y + z = 0$

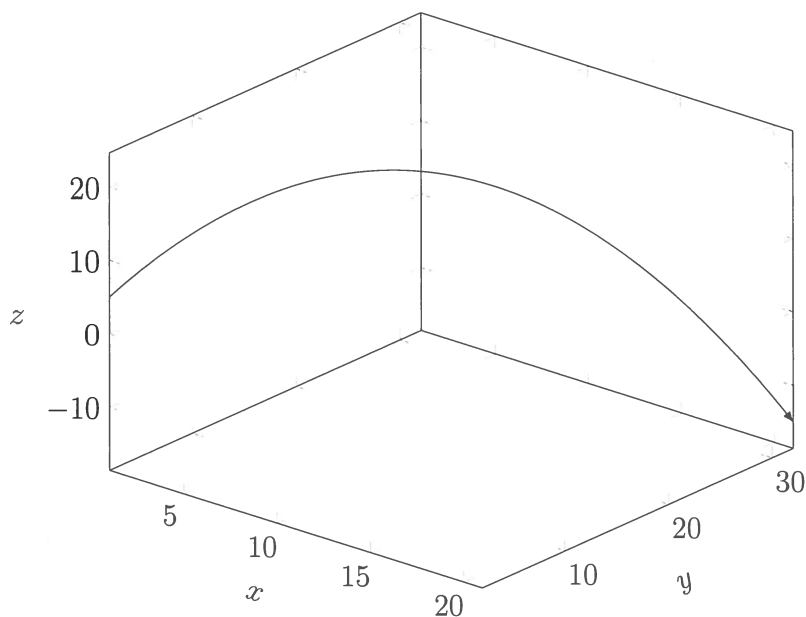
Consider the plane in 3D-space with equation $2x - y + 3z = 6$ and the line with parametric equation $(x, y, z) = (1, 0, 2) + t(-1, 3, 1)$. The plane and the line intersect at a point.

- 7.d. (4 points) Find the coordinates of the point of intersection. $(0, 3, 3)$

Problem 8. The position vector of a moving particle in 3D-space is given by

$$\vec{r}(t) = (3t + 1, 4t + 2, -t^2 + 8t + 5).$$

Here is a plot of the motion curve when the time t runs from 0 to 10:



- 8.a. (3 points) Compute the velocity vector $\vec{v}(t)$. $\vec{v}(t) = (3, 4, -2t + 8)$
 8.b. (2 points) Compute the speed $v(t)$. $v(t) = \sqrt{25 + (-2t + 8)^2}$
 8.c. (1 points) Find the speed at time $t = 4$. $v(4) = 5$
 8.d. (3 points) Find a unit vector, which points in the direction that the particle is moving at time $t = 4$. $(\frac{3}{5}, \frac{4}{5}, 0)$

$$9b \quad \left[\begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 2 & 3 & 1 & 4 \\ 1 & 2 & 0 & 3 \end{array} \right]$$

$$9c \quad \left[\begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$9d \quad \left[\begin{array}{ccc|c} 1 & 0 & 2 & -1 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Problem 9. Consider the following system of linear equations:

$$\begin{aligned} x_1 + x_2 + x_3 &= 1 \\ 2x_1 + 3x_2 + x_3 &= 4 \\ x_1 + 2x_2 &= 3 \end{aligned}$$

- 9.a. (2 points) Is $x_1 = 2, x_2 = 1, x_3 = 1$ a solution of the system? Why/why not? *No, insert.*
- 9.b. (2 points) Find the augmented matrix of the system.
- 9.c. (4 points) Find a row echelon form of the augmented matrix.
- 9.d. (2 points) Find the reduced row echelon form of the augmented matrix.
- 9.e. (4 points) Write down the general solution of the system.
- 9.f. (3 points) Find a solution of the system which has $x_3 = -1$.

$$\begin{cases} x_1 = -1 - 2x_3 \\ x_2 = 2 + x_3 \\ x_3 \text{ free} \end{cases}$$

$$\begin{cases} x_1 = 1 \\ x_2 = 1 \\ x_3 = -1 \end{cases}$$

Problem 10. Define two matrices as follows:

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 3 & 1 \\ 0 & 7 & 0 \\ 2 & 6 & 2 \end{bmatrix}$$

- 10.a. (2 points) Compute $2A + B$.
- 10.b. (3 points) Compute the matrix product AB .
- 10.c. (3 points) Determine whether A is invertible. If so, find its inverse.
- 10.d. (3 points) Determine whether B is invertible. If so, find its inverse.

$$\begin{bmatrix} 3 & 3 & 3 \\ 0 & 7 & 0 \\ 0 & 6 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 9 & 3 \\ 0 & 7 & 0 \\ -1 & -3 & -1 \end{bmatrix}$$

10c A is invertible and $A^{-1} = \begin{bmatrix} 0 & 0 & -1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$.

10d B is not invertible.

Appendix

Exact values for trigonometric functions of various angles.

	30°	45°	60°
	$\frac{\pi}{6}$	$\frac{\pi}{4}$	$\frac{\pi}{3}$
sin	$\frac{1}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{3}}{2}$
cos	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{1}{2}$
tan	$\frac{\sqrt{3}}{3}$	1	$\sqrt{3}$