

## 14. Session: Matrices and Vectors

Def.: An  $m \times n$ -matrix A is a rectangular array of real numbers with m rows and n columns.

Ex.

$$A = \begin{bmatrix} 7 & 2 \\ 5 & 0 \\ -1 & 11 \end{bmatrix} \quad 3 \times 2\text{-matrix}$$

$$\begin{bmatrix} 8 & 0 & 7 \\ 5 & -1 & 10 \\ 2 & \sqrt{5} & 7 \end{bmatrix} \quad 3 \times 3\text{-matrix}$$

$$\begin{bmatrix} 1 \\ 3 \end{bmatrix} \quad 2 \times 1\text{-matrix}$$

Def.: The number in the  $i^{\text{th}}$  row and  $j^{\text{th}}$  column of A is called the  $(i, j)$ -entry and denoted  $a_{ij}$  or  $[A]_{ij}$ .

Ex.

$$A = \begin{matrix} & \begin{matrix} 1 & 2 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} 7 & 2 \\ 5 & 0 \\ -1 & 11 \end{bmatrix} \end{matrix} \quad [A]_{11} = 7, [A]_{12} = 2 \\ [A]_{21} = 5, [A]_{22} = 0 \\ [A]_{31} = -1, [A]_{32} = 11$$

Def.: Let A and B be  $m \times n$ -matrices and let c be a scalar\*. Then  $A+B$ ,  $A-B$  and  $cA$  are the  $m \times n$ -matrices with entries as follows :

$$[A+B]_{ij} = [A]_{ij} + [B]_{ij},$$

$$[A-B]_{ij} = [A]_{ij} - [B]_{ij},$$

$$[cA]_{ij} = c[A]_{ij},$$

for  $i=1,2,3,\dots,m$  and  $j=1,2,3,\dots,n$ . The zero-matrix  $O$  is the  $m \times n$ -matrix with  $[O]_{ij} = 0$  for every i and j.

\* "Scalar" means real number

Ex.

$$\begin{bmatrix} 3 & 4 & 2 \\ 2 & -3 & 0 \end{bmatrix} + \begin{bmatrix} -4 & 1 & 0 \\ 5 & -6 & 1 \end{bmatrix} = \begin{bmatrix} 3+(-4) & 4+1 & 2+0 \\ 2+5 & -3+(-6) & 0+1 \end{bmatrix} = \begin{bmatrix} -1 & 5 & 2 \\ 7 & -9 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 4 & 2 \\ 2 & -3 & 0 \end{bmatrix} - \begin{bmatrix} -4 & 1 & 0 \\ 5 & -6 & 1 \end{bmatrix} = \begin{bmatrix} 3-(-4) & 4-1 & 2-0 \\ 2-5 & -3-(-6) & 0-1 \end{bmatrix} = \begin{bmatrix} 7 & 3 & 2 \\ -3 & 3 & -1 \end{bmatrix}$$

$$3 \cdot \begin{bmatrix} 3 & 4 & 2 \\ 2 & -3 & 0 \end{bmatrix} = \begin{bmatrix} 3 \cdot 3 & 3 \cdot 4 & 3 \cdot 2 \\ 3 \cdot 2 & 3 \cdot (-3) & 3 \cdot 0 \end{bmatrix} = \begin{bmatrix} 9 & 12 & 6 \\ 6 & -9 & 0 \end{bmatrix}.$$

Theorem: Let  $A, B, C$  be  $m \times n$ -matrices and let  $s, t$  be scalars. Then

- (1)  $A+B = B+A$  (2)  $(A+B)+C = A+(B+C)$
- (3)  $A+O = A$  (4)  $A-A = O$
- (5)  $(st)A = s(tA)$  (6)  $s(A+B) = sA+sB$
- (7)  $(s+t)A = sA+tA.$

Proof of (1): Both sides are  $m \times n$ -matrices, and  $[A+B]_{ij} = [A]_{ij} + [B]_{ij} = [B]_{ij} + [A]_{ij} = [B+A]_{ij}$ . q.e.d

Def.: Let  $A$  be an  $m \times n$ -matrix. The transpose of  $A$  is the  $n \times m$ -matrix  $A^T$  with

$$[A^T]_{ij} = [A]_{ji}$$

for  $i=1,2,\dots,n$  and  $j=1,2,\dots,m$ .

Note: The columns of  $A^T$  are the rows of  $A$ , and vice versa.

Ex.  $\begin{bmatrix} 3 & 4 & 2 \\ 2 & -3 & 0 \end{bmatrix}^T = \begin{bmatrix} 3 & 2 \\ 4 & -3 \\ 2 & 0 \end{bmatrix},$

$$\begin{bmatrix} 1 & 7 \\ -2 & 0 \end{bmatrix}^T = \begin{bmatrix} 1 & -2 \\ 7 & 0 \end{bmatrix},$$

$$\begin{bmatrix} 5 \\ -3 \end{bmatrix}^T = [5 \ -3].$$

Theorem: Let  $A$  and  $B$  be  $m \times n$ -matrices, and let  $s$  be a scalar. Then

$$(1) \quad (A+B)^T = A^T + B^T$$

$$(2) \quad (sA)^T = s(A^T)$$

$$(3) \quad (A^T)^T = A.$$

Def. An  $1 \times n$ -matrix is called a row vector.

An  $m \times 1$ -matrix is called a column vector.

Ex.  $\begin{bmatrix} 5 & 0 & -1 \end{bmatrix}$  row vector

$$\begin{bmatrix} 2 \\ 7 \end{bmatrix} \quad \text{column vector}$$

Note: We usually work with column vectors.

Ex.  $\begin{bmatrix} 2 \\ 7 \end{bmatrix} + \begin{bmatrix} -1 \\ 3 \end{bmatrix} = \begin{bmatrix} 2+(-1) \\ 7+3 \end{bmatrix} = \begin{bmatrix} 1 \\ 10 \end{bmatrix},$

$$5 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 5 \cdot 1 \\ 5 \cdot 3 \end{bmatrix} = \begin{bmatrix} 5 \\ 15 \end{bmatrix}.$$

Def. A linear combination of the  $m \times 1$ -vectors

$\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k$  is a vector of the form

$$c_1 \vec{u}_1 + c_2 \vec{u}_2 + \dots + c_k \vec{u}_k,$$

where  $c_1, c_2, \dots, c_k$  are scalars. These scalars are called the coefficients or weights of the linear combination.

Ex.

$$1 \cdot \begin{bmatrix} 1 \end{bmatrix} + 2 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} + (-1) \begin{bmatrix} 1 \\ -1 \end{bmatrix} =$$

$$\begin{bmatrix} 1 \end{bmatrix} + \begin{bmatrix} 2 \\ 6 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 8 \end{bmatrix}$$

Thus,  $\begin{bmatrix} 2 \\ 8 \end{bmatrix}$  is a linear combination of the vectors  $\begin{bmatrix} 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ .

Ex. Is  $\begin{bmatrix} 4 \\ -1 \end{bmatrix}$  a linear combination of  $\begin{bmatrix} 2 \\ 3 \end{bmatrix}$  and  $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ ?

$$x \begin{bmatrix} 2 \\ 3 \end{bmatrix} + y \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \end{bmatrix} \Leftrightarrow \begin{bmatrix} 2x+3y \\ 3x+y \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \end{bmatrix} \Leftrightarrow \begin{cases} 2x+3y=4 \\ 3x+y=-1 \end{cases}$$

$$\begin{cases} 2x+3y=4 \\ y=-3x-1 \end{cases} \Leftrightarrow \begin{cases} 2x+3(-3x-1)=4 \\ y=-3x-1 \end{cases} \Leftrightarrow \begin{cases} -7x=7 \\ y=-3x-1 \end{cases} \Leftrightarrow \begin{cases} x=-1 \\ y=2 \end{cases}$$

$$\text{Yes, } (-1) \begin{bmatrix} 2 \\ 3 \end{bmatrix} + 2 \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \end{bmatrix}.$$

Notation: The set of column vectors with  $m$  coordinates is denoted  $\mathbb{R}^m$ . Thus, a vector  $\vec{v}$  in  $\mathbb{R}^m$  has the form

$$\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix}.$$

Def. The standard basis vectors in  $\mathbb{R}^m$  are

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \quad \dots, \quad \vec{e}_m = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$$

Ex. Standard basis vectors in  $\mathbb{R}^2$ :

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \vec{i}, \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \vec{j}.$$

Ex. Standard basis vectors in  $\mathbb{R}^3$ :

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \vec{i}, \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \vec{j}, \quad \vec{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \vec{k}.$$

Note that

$$\begin{bmatrix} x \\ y \end{bmatrix} = x\vec{i} + y\vec{j},$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = x\vec{i} + y\vec{j} + z\vec{k},$$

$$\vec{v} = v_1 \vec{e}_1 + v_2 \vec{e}_2 + \dots + v_m \vec{e}_m.$$